

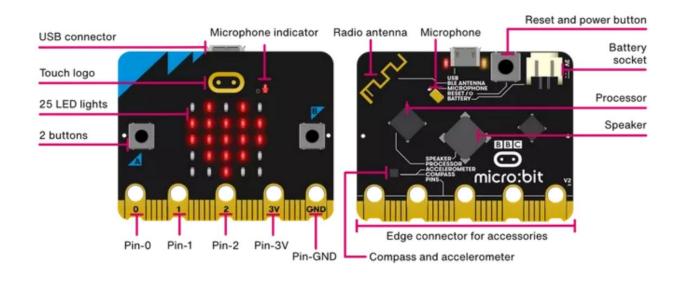
Want to start coding? Go to https://makecode.microbit.org/

| INPUTS | | |
|----------------------------------|------|--|
| Input Blocks Overview | Pg 3 | |
| Buttons | Pg 4 | |
| Accelerometer | Pg 4 | |
| Temperature sensor | Pg 5 | |
| Light sensor | Pg 5 | |
| Logo | Pg 6 | |
| Touch/connectivity sensor (pins) | Pg 6 | |
| External distance sensor | Pg 7 | |

CODE
Activates certain
outputs when the
input conditions
are how you want
them

| OUTPUTS | |
|-------------------------|------|
| Basic Blocks | Pg 2 |
| LED screen | Pg 2 |
| Sounds | Pg8 |
| Recording Audio | Pg 8 |
| External LED Light | Pg 9 |
| External Servo Motor | Pg 9 |

| OTHER | |
|-------------------------------|-------|
| Downloading to your micro:bit | Pg 2 |
| Logic & Loops | Pg 3 |
| Variables | Pg 10 |
| Radio | Pg 10 |





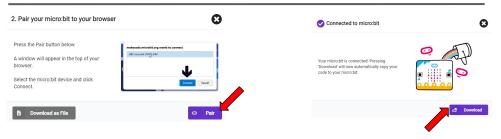
Downloading to your micro:bit

See your code in action

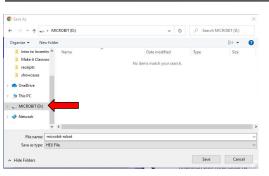


- Step 1: Turn the switch on the micro:bit batteries to OFF
- <u>Step 2</u>: Use the USB cord to connect the micro:bit to your computer





- Step 4: Follow the instructions on the screen to Pair your micro:bit with the computer.
- <u>Step 5</u>: Once connected to micro:bit, press the download button. Your download should start, and the yellow light on your micro:bit should flash.
- <u>Step 6</u>: When the light stops flashing, disconnect your micro:bit from the computer and turn the batteries on.



Something didn't work? Try this next.

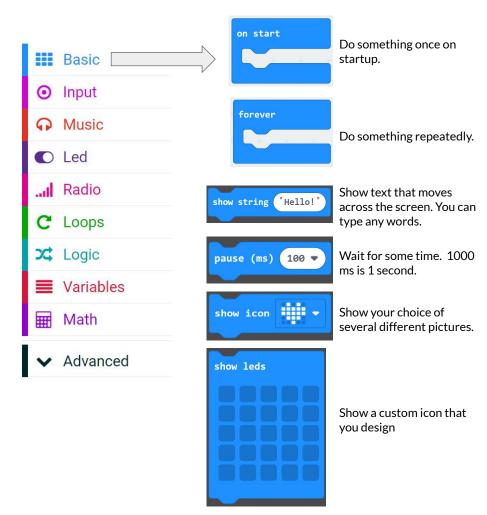
<u>Step 7:</u> Click Download as File. Make sure the code file is downloading to the micro:bit, not your computer. The light on the back of the micro:bit will flash.



Micro:bit Cheat Sheets

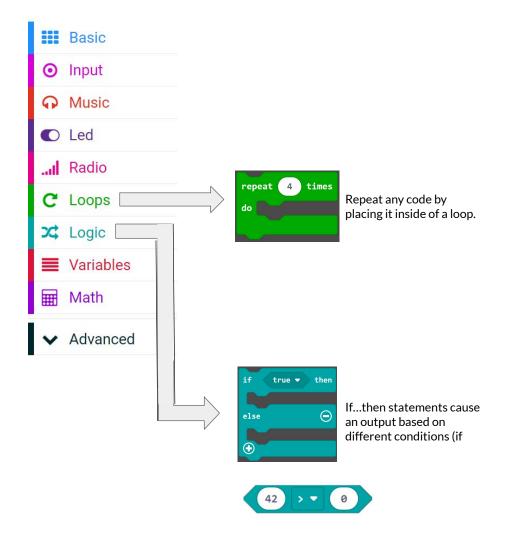
Basic Blocks

Display things on the screen and control timing



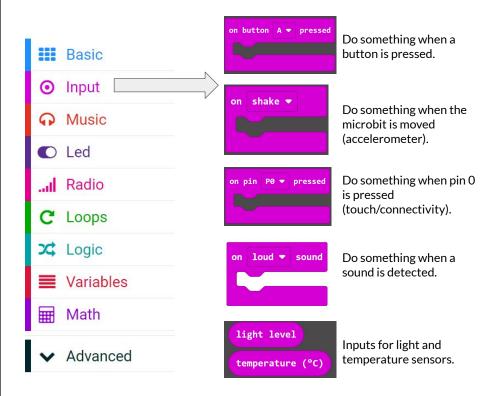


Other Useful Blocks





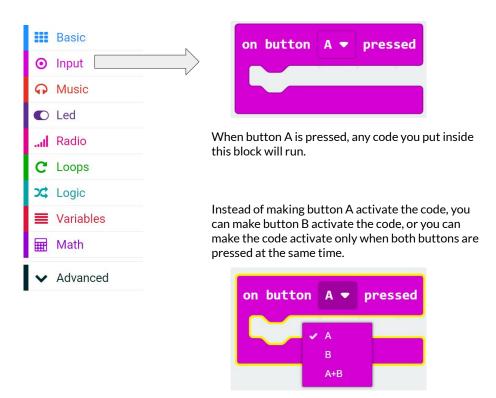
Input Blocks Choose things to start other code





Input

Button React to being pressed



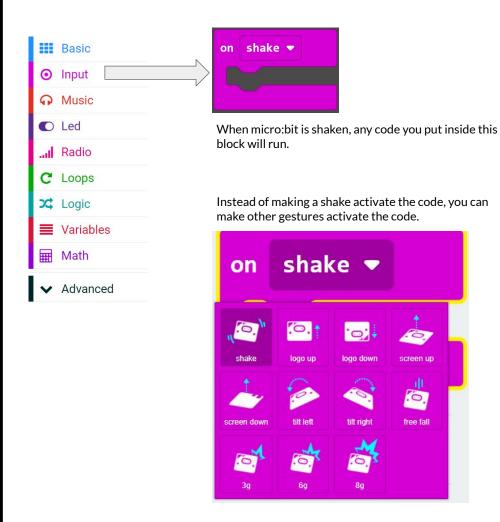


Micro:bit Cheat Sheets

Input (Sensor)

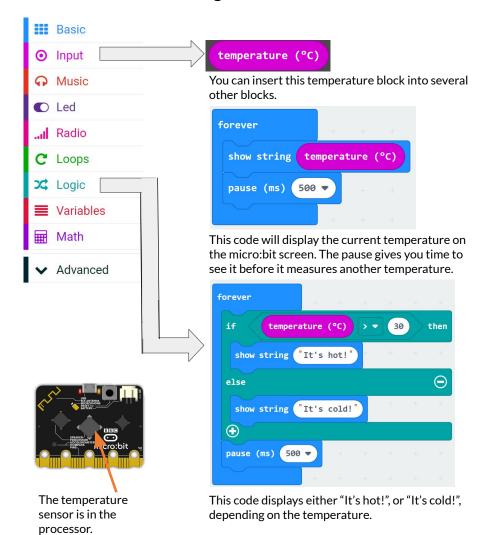
Accelerometer

Know when the micro:bit moves



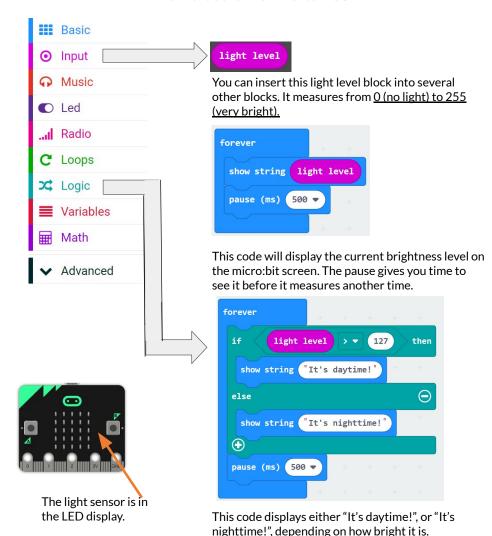
Temperature Sensor

Determine how hot or cold the room/world is, in degrees Celsius.





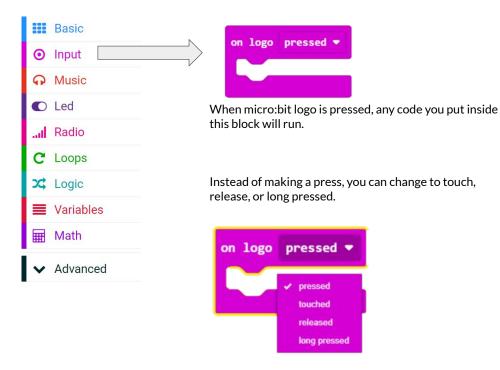
Determine how bright or dark the room/world is, on a scale from 0 to 255





Input (Sensor)

Logo Know when the micro:bit logo in touched



With touched or released, you may need to use a pause block as part of your code, so that the code has time to run after the input is triggered.



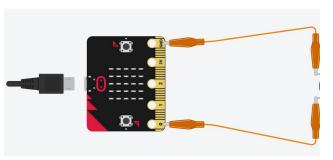
forever

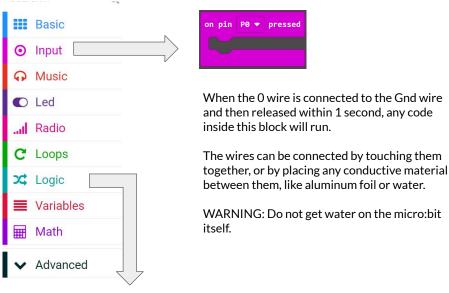
Micro:bit Cheat Sheets

Input (Sensor)

Touch/Connectivity Sensor

Know when two wires are connected to pins





This code continually runs the code you place

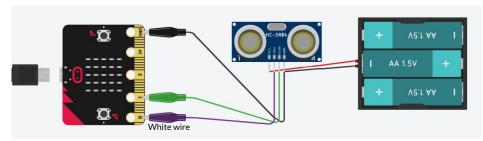
inside of it for as long as the two wires are

touching.

Input (Sensor)

External Distance Sensor

Measure how far away a target is





Search "sonar" and add the sonar extension.

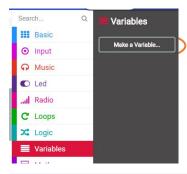


On the main screen, go to the sonar menu. There is one option for a block to use.



ping trig = where you connected your white wire echo = where you connected your green wire units = change this to cm (centimeters)

Distance Sensor continued



To show on the screen how far the distance sensor is from an object, you need to create a variable. Name it "distance"



Then, use your sonor block and distance variable. This code shows the distance to an object when button A is pressed.

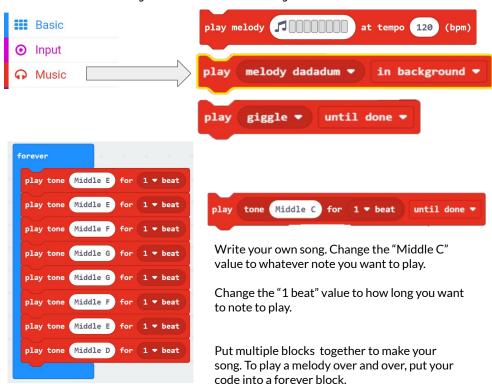


This code shows different messages depending how far away the object is.

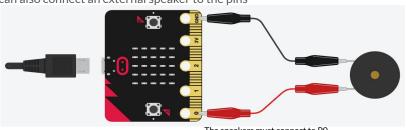
You can change the "show string" block to any code (including moving the servo).

Sounds

Play musical notes of your choice



You can also connect an external speaker to the pins

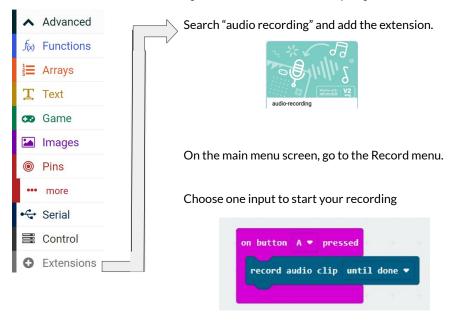


The speakers must connect to PO



Recording Audio

Create your own sound to play



Choose another input to play your recording

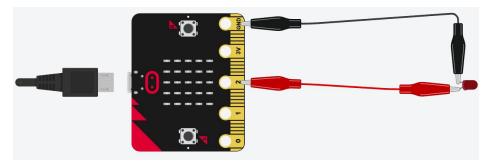


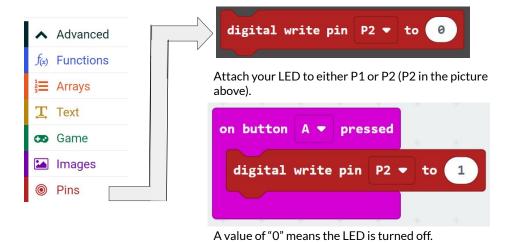
Note: the micro:bit can only store one recording at a time, so if you re-record, it will erase your previous recording.



External LED Light

Illuminate a separate light from the Micro:bit



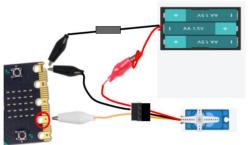


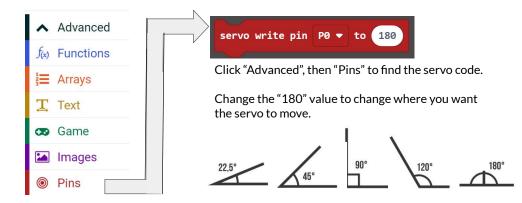
A value of "1" means the LED is turned on.



Servo Motor

Rotate to a position of your choice







This code moves the servo back and forth. The pause gives the motor time to get to the location, before moving to the next spot.

The forever means the motor will keep moving back the forth. You can use a different block here (like On Button A).



Variables

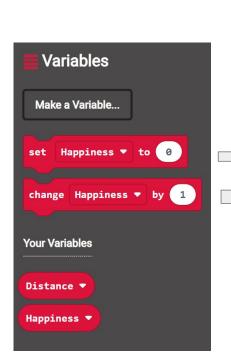
Create and measure values for sets of data

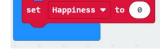


The variable menu will start out empty.

Create and name the new variable that needs to be measured.

on start





This block gives your variable a number value to start with.



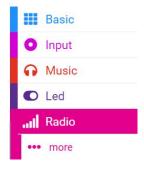
This block will change/add the value (every second) by the number in the white bubble.

Any created variables are now listed here. These will be the choices available in the drop down menu.



Micro:bit Cheat Sheets

Radio Send radio signals to other micro:bits





Micro:bits communicate by being in the same radio group. Place this block in a "forever" or "on start" block. Choose a group number (1-50) and type it into the bubble. Check that your group number is the same as the micro:bit you want to send messages to.

Sending Messages

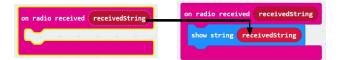


To send the first message, attach one of these blocks into a "input" block. Then write a simple message.



Receiving Messages

Use the "on radio received block" to accept the message. To read the message, drag the "receivedString" bubble and place it in a "show string" block.





If you want to send a response, add the "radio send string" block with your message.